

Convexifying positive polynomials and a proximity algorithm

Krzysztof Kurdyka Stanisław Spodzieja
Université Savoie Mont Blanc University of Łódź

MEGA 2017, Nice

- We prove that if f is a positive C^2 function on a convex compact set $X \subset \mathbb{R}^n$ then

$$\varphi_N = f(x)(1 + |x|^2)^N$$

is strongly convex for N large enough.

- For f polynomial we give an explicit estimate for N , which depends on the size of the coefficients of f and on the lower bound of f on X .
- Application: an algorithm which for a given polynomial f on a convex compact **semialgebraic** set X produces a sequence (starting from an arbitrary point in X) which converges to a (lower) critical point of f on X . The convergence is based on the method of talweg which is a generalization of the Łojasiewicz gradient inequality

$$|\nabla f| \geq |f|^\rho,$$

with $\rho < 1$ for f analytic in a ngbh. of $0 \in \mathbb{R}^n$, $f(0) = 0$.

- We prove that if f is a positive C^2 function on a convex compact set $X \subset \mathbb{R}^n$ then

$$\varphi_N = f(x)(1 + |x|^2)^N$$

is strongly convex for N large enough.

- For f polynomial we give an explicit estimate for N , which depends on the size of the coefficients of f and on the lower bound of f on X .
- Application: an algorithm which for a given polynomial f on a convex compact **semialgebraic** set X produces a sequence (starting from an arbitrary point in X) which converges to a (lower) critical point of f on X . The convergence is based on the method of talweg which is a generalization of the Łojasiewicz gradient inequality

$$|\nabla f| \geq |f|^\rho,$$

with $\rho < 1$ for f analytic in a ngbh. of $0 \in \mathbb{R}^n$, $f(0) = 0$.

- We prove that if f is a positive C^2 function on a convex compact set $X \subset \mathbb{R}^n$ then

$$\varphi_N = f(x)(1 + |x|^2)^N$$

is strongly convex for N large enough.

- For f polynomial we give an explicit estimate for N , which depends on the size of the coefficients of f and on the lower bound of f on X .
- Application: an algorithm which for a given polynomial f on a convex compact **semialgebraic** set X produces a sequence (starting from an arbitrary point in X) which converges to a (lower) critical point of f on X . The convergence is based on the method of talweg which is a generalization of the Łojasiewicz gradient inequality

$$|\nabla f| \geq |f|^\rho,$$

with $\rho < 1$ for f analytic in a ngbh. of $0 \in \mathbb{R}^n$, $f(0) = 0$.

We denote by $\mathbb{R}[x]$ or $\mathbb{R}[x_1, \dots, x_n]$ the ring of polynomials in $x = (x_1, \dots, x_n)$ with coefficients in \mathbb{R} .

A set $X \subset \mathbb{R}^n$ is called *semialgebraic* if it is a finite union of sets of the form

$$\{x \in \mathbb{R}^n : g_1(x) \geq 0, \dots, g_j(x) \geq 0, g_{j+1}(x) > 0, \dots, g_r(x) > 0\},$$

where $g_1, \dots, g_r \in \mathbb{R}[x]$.

We denote by $\mathbb{R}[x]$ or $\mathbb{R}[x_1, \dots, x_n]$ the ring of polynomials in $x = (x_1, \dots, x_n)$ with coefficients in \mathbb{R} .

A set $X \subset \mathbb{R}^n$ is called *semialgebraic* if it is a finite union of sets of the form

$$\{x \in \mathbb{R}^n : g_1(x) \geq 0, \dots, g_j(x) \geq 0, g_{j+1}(x) > 0, \dots, g_r(x) > 0\},$$

where $g_1, \dots, g_r \in \mathbb{R}[x]$.

Convexifying

The aim of the lecture is convexification of polynomials.

Let X be a **convex closed semialgebraic subset** of \mathbb{R}^n
and let f be a **polynomial which is positive on X** .

We give necessary and sufficient conditions for the existence of an exponent $N \in \mathbb{N}$ such that

$(1 + |x|^2)^N f(x)$ is a **strongly convex** function on X .

A C^1 function $g : X \rightarrow \mathbb{R}$ is called μ -**strongly convex** if

$$g(y) \geq g(x) + \langle y - x, \nabla g(x) \rangle + \frac{\mu}{2} |y - x|^2 \quad \text{for } x, y \in X,$$

where $\mu > 0$ and $\langle \cdot, \cdot \rangle$ is the standard scalar product.

Convexifying

The aim of the lecture is convexification of polynomials.

Let X be a **convex closed semialgebraic subset** of \mathbb{R}^n
and let f be a **polynomial which is positive on X** .

We give necessary and sufficient conditions for the existence of an exponent $N \in \mathbb{N}$ such that

$(1 + |x|^2)^N f(x)$ is a **strongly convex** function on X .

A C^1 function $g : X \rightarrow \mathbb{R}$ is called μ -**strongly convex** if

$$g(y) \geq g(x) + \langle y - x, \nabla g(x) \rangle + \frac{\mu}{2} |y - x|^2 \quad \text{for } x, y \in X,$$

where $\mu > 0$ and $\langle \cdot, \cdot \rangle$ is the standard scalar product.

Convexifying

The aim of the lecture is convexification of polynomials.

Let X be a **convex closed semialgebraic subset** of \mathbb{R}^n
and let f be a **polynomial which is positive on X** .

We give necessary and sufficient conditions for the existence of an exponent $N \in \mathbb{N}$ such that

$(1 + |x|^2)^N f(x)$ is a **strongly convex** function on X .

A C^1 function $g : X \rightarrow \mathbb{R}$ is called μ -**strongly convex** if

$$g(y) \geq g(x) + \langle y - x, \nabla g(x) \rangle + \frac{\mu}{2} |y - x|^2 \quad \text{for } x, y \in X,$$

where $\mu > 0$ and $\langle \cdot, \cdot \rangle$ is the standard scalar product.

The key point in further considerations is the following lemma.

Lemma (1)

Let $f \in \mathbb{R}[t]$, and let f be positive on a closed interval $I \subset \mathbb{R}$.
Then there exists $N_0 \in \mathbb{N}$ such that for any $N \geq N_0$ the polynomial

$$\varphi_N(t) := (1 + t^2)^N f(t)$$

is strongly convex on I .

Remark (2)

Let $f(t) = \sum_{i=0}^d a_i t^{d-i}$, $a_0 \neq 0$. Then we can take

$$N_0 = [\mathcal{N}(m, K, D)] + 1,$$

where $\mathcal{N}(m, K, D) := \max \left\{ \frac{D}{m} + \frac{m}{16D}, \frac{(1+K^2)D}{Km} + 1, \frac{4D^2}{m^2} + 2, \frac{(1+K^2)D}{2m} \right\}$.

$$K = 1 + 2 \max_{1 \leq i \leq d} |a_i/a_0|^{1/i}, \quad m = \min\{f(t) : t \in I\},$$

$$|f'(t)| \leq D, \quad |f''(t)| \leq D \quad \text{for } |t| \leq K.$$

The key point in further considerations is the following lemma.

Lemma (1)

Let $f \in \mathbb{R}[t]$, and let f be positive on a closed interval $I \subset \mathbb{R}$. Then there exists $N_0 \in \mathbb{N}$ such that for any $N \geq N_0$ the polynomial

$$\varphi_N(t) := (1 + t^2)^N f(t)$$

is strongly convex on I .

Remark (2)

Let $f(t) = \sum_{i=0}^d a_i t^{d-i}$, $a_0 \neq 0$. Then we can take

$$N_0 = [\mathcal{N}(m, K, D)] + 1,$$

where $\mathcal{N}(m, K, D) := \max \left\{ \frac{D}{m} + \frac{m}{16D}, \frac{(1+K^2)D}{Km} + 1, \frac{4D^2}{m^2} + 2, \frac{(1+K^2)D}{2m} \right\}$.

$$K = 1 + 2 \max_{1 \leq i \leq d} |a_i/a_0|^{1/i}, \quad m = \min\{f(t) : t \in I\},$$

$$|f'(t)| \leq D, \quad |f''(t)| \leq D \quad \text{for } |t| \leq K.$$

Convexifying polynomials on compact sets

Theorem (KS 2015)

Let $f \in \mathbb{R}[x]$ be positive on a compact convex set $X \subset \mathbb{R}^n$. Then there exists $N_0 \in \mathbb{N}$ such that for any integer $N \geq N_0$ the polynomial

$$\varphi_N(x) = (1 + x_1^2 + \cdots + x_n^2)^N f(x)$$

is strongly convex in X .

Sketch of the proof. Let $R = \max\{|x| : x \in X\}$, and let

$$\mathcal{A} = \{(\alpha, \beta) \in \mathbb{R}^n \times \mathbb{R}^n : \langle \alpha, \beta \rangle = 0, |\alpha| \leq R, |\beta| = 1\}.$$

$$\gamma_{\alpha, \beta}(t) := \sqrt{1 + |\alpha|^2} \beta t + \alpha.$$

Clearly the family of all $\gamma_{\alpha, \beta}$ with $(\alpha, \beta) \in \mathcal{A}$ parametrizes all affine lines in \mathbb{R}^n which may intersect X . Since

$$\varphi_N \circ \gamma_{\alpha, \beta}(t) = (1 + |\alpha|^2)^N (1 + t^2)^N f \circ \gamma_{\alpha, \beta}(t),$$

applying Lemma 1 we deduce the assertion. □

Convexifying polynomials on compact sets

Theorem (KS 2015)

Let $f \in \mathbb{R}[x]$ be positive on a compact convex set $X \subset \mathbb{R}^n$. Then there exists $N_0 \in \mathbb{N}$ such that for any integer $N \geq N_0$ the polynomial

$$\varphi_N(x) = (1 + x_1^2 + \cdots + x_n^2)^N f(x)$$

is strongly convex in X .

Sketch of the proof. Let $R = \max\{|x| : x \in X\}$, and let

$$\mathcal{A} = \{(\alpha, \beta) \in \mathbb{R}^n \times \mathbb{R}^n : \langle \alpha, \beta \rangle = 0, |\alpha| \leq R, |\beta| = 1\}.$$

$$\gamma_{\alpha, \beta}(t) := \sqrt{1 + |\alpha|^2} \beta t + \alpha.$$

Clearly the family of all $\gamma_{\alpha, \beta}$ with $(\alpha, \beta) \in \mathcal{A}$ parametrizes all affine lines in \mathbb{R}^n which may intersect X . Since

$$\varphi_N \circ \gamma_{\alpha, \beta}(t) = (1 + |\alpha|^2)^N (1 + t^2)^N f \circ \gamma_{\alpha, \beta}(t),$$

applying Lemma 1 we deduce the assertion. □

Does convexity of φ_{N_0} imply convexity of all φ_N for $N \geq N_0$?

No, namely we have

Example

Let $f(x) = 7x^2 - 22x + 19$. The polynomial f is strictly positive on \mathbb{R} .
Moreover,

$$\varphi_N''(1) = 2^{N+1}[2N^2 - 8N + 7].$$

Then $\varphi_1''(1) = 4$, $\varphi_2''(1) = -8$, and $\varphi_3''(1) = 16$. Hence, there exists a closed interval $I \subset \mathbb{R}$ centered at 1 such that

- $\varphi_1''(x) > 0$ for $x \in I$, so φ_1 is strongly convex in I ,
- $\varphi_2''(x) < 0$ for $x \in I$, so φ_2 is strongly concave in I ,
- $\varphi_3''(x) > 0$ for $x \in I$, so φ_3 is strongly convex in I .

Does convexity of φ_{N_0} imply convexity of all φ_N for $N \geq N_0$?

No, namely we have

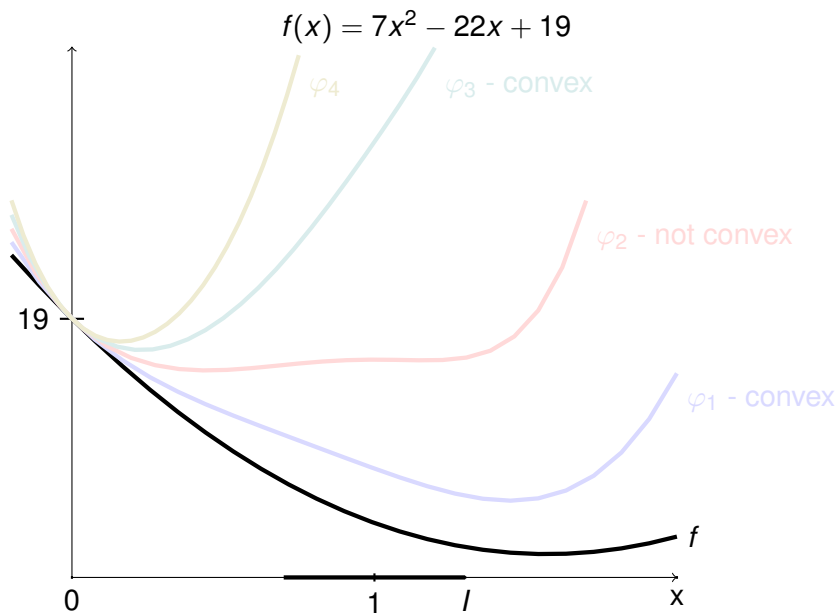
Example

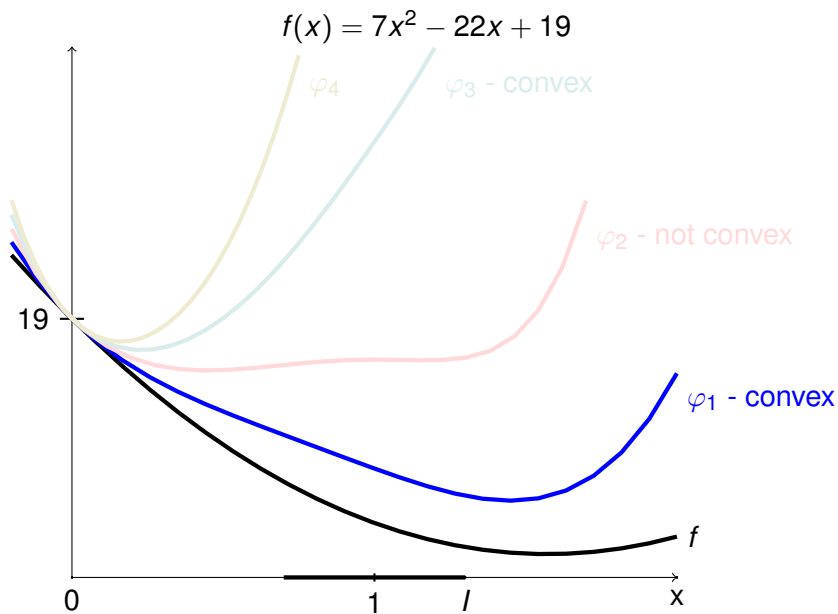
Let $f(x) = 7x^2 - 22x + 19$. The polynomial f is strictly positive on \mathbb{R} .
Moreover,

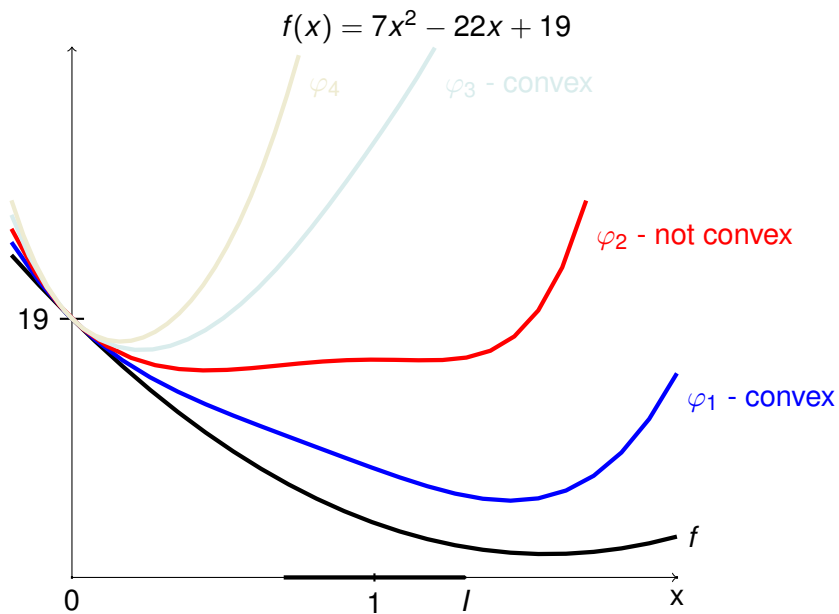
$$\varphi_N''(1) = 2^{N+1}[2N^2 - 8N + 7].$$

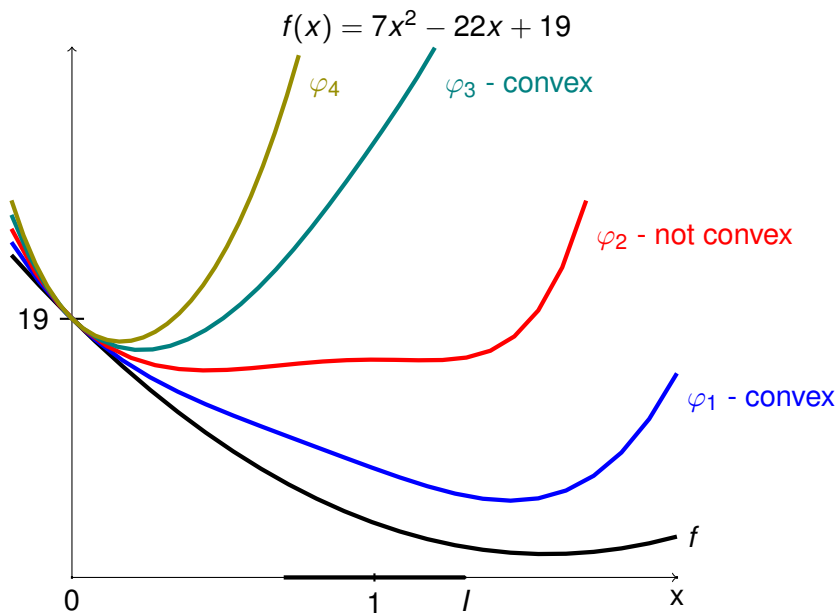
Then $\varphi_1''(1) = 4$, $\varphi_2''(1) = -8$, and $\varphi_3''(1) = 16$. Hence, there exists a closed interval $I \subset \mathbb{R}$ centered at 1 such that

- $\varphi_1''(x) > 0$ for $x \in I$, so φ_1 is strongly convex in I ,
- $\varphi_2''(x) < 0$ for $x \in I$, so φ_2 is strongly concave in I ,
- $\varphi_3''(x) > 0$ for $x \in I$, so φ_3 is strongly convex in I .









Let p be homogeneous polynomial which is *positive definite* i.e., $p(x) > 0$ for $x \in \mathbb{R}^n \setminus \{0\}$. Reznick proved that for some positive integer K , the polynomial $p|x|^{2K}$ belongs to the cone $Q_{n,k}$ of finite sums of k th powers of linear function, where $k = \deg p + 2K$. Hence $p|x|^{2K}$ is *convex*. More precisely, he proved the following

Theorem (Reznick1995)

Let p be a positive definite homogeneous polynomial of degree d . Then for any $K \in \mathbb{N}$ such that

$$K \geq \frac{nd(d-1)}{(4 \log 2)\epsilon(p)} - \frac{n+1}{2}$$

we have $p(x)|x|^{2K} \in Q_{n,d+2K}$, where

$$\epsilon(p) := \frac{\inf\{p(u) : u \in S\}}{\sup\{p(u) : u \in S\}},$$

and $S = \{x \in \mathbb{R}^n : |x| = 1\}$ is the unit sphere.

A proximity algorithm for a polynomial on a convex set

Let f be a C^1 function in a neighborhood U of a closed set $X \subset \mathbb{R}^n$.

Recall that $a \in X$ is a **lower critical point of f on X** if

$$\langle \nabla f(a), x - a \rangle \geq 0 \quad \text{for any } x \in X \text{ in a ngbh. of } a.$$

We denote by $\Sigma_X f$ the set of lower critical points of f on X , and by $\Sigma f := \{x \in U : \nabla f(x) = 0\}$ the set of ordinary critical points of f .

Proposition (4)

If $X \subset \mathbb{R}^n$ is closed convex and $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is a C^1 function, then:

- 1 $X \cap \Sigma f \subset \Sigma_X f$;
- 2 if f restricted to X has a local minimum at a , then $a \in \Sigma_X f$;
- 3 if $M \subset X$ is a smooth manifold and $a \in M \cap \Sigma_X f$, then for any $z \in T_a M$,

$$\langle \nabla f(a), z \rangle = 0;$$

- 4 if f is a polynomial and X is semialgebraic, then $\Sigma_X f$ is a semialgebraic set and $f(\Sigma_X f)$ is a finite set.

A proximity algorithm for a polynomial on a convex set

Let f be a C^1 function in a neighborhood U of a closed set $X \subset \mathbb{R}^n$.

Recall that $a \in X$ is a **lower critical point of f on X** if

$$\langle \nabla f(a), x - a \rangle \geq 0 \quad \text{for any } x \in X \text{ in a ngbh. of } a.$$

We denote by $\Sigma_X f$ **the set of lower critical points** of f on X , and by $\Sigma f := \{x \in U : \nabla f(x) = 0\}$ **the set of ordinary critical points** of f .

Proposition (4)

If $X \subset \mathbb{R}^n$ is closed convex and $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is a C^1 function, then:

- 1 $X \cap \Sigma f \subset \Sigma_X f$;
- 2 *if f restricted to X has a local minimum at a , then $a \in \Sigma_X f$;*
- 3 *if $M \subset X$ is a smooth manifold and $a \in M \cap \Sigma_X f$, then for any $z \in T_a M$,*

$$\langle \nabla f(a), z \rangle = 0;$$

- 4 *if f is a polynomial and X is semialgebraic, then $\Sigma_X f$ is a semialgebraic set and $f(\Sigma_X f)$ is a finite set.*

A proximity algorithm for a polynomial on a convex set

Let f be a C^1 function in a neighborhood U of a closed set $X \subset \mathbb{R}^n$.

Recall that $a \in X$ is a **lower critical point of f on X** if

$$\langle \nabla f(a), x - a \rangle \geq 0 \quad \text{for any } x \in X \text{ in a ngbh. of } a.$$

We denote by $\Sigma_X f$ **the set of lower critical points** of f on X , and by $\Sigma f := \{x \in U : \nabla f(x) = 0\}$ **the set of ordinary critical points** of f .

Proposition (4)

If $X \subset \mathbb{R}^n$ is closed convex and $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is a C^1 function, then:

- 1 $X \cap \Sigma f \subset \Sigma_X f$;
- 2 *if f restricted to X has a local minimum at a , then $a \in \Sigma_X f$;*
- 3 *if $M \subset X$ is a smooth manifold and $a \in M \cap \Sigma_X f$, then for any $z \in T_a M$,*

$$\langle \nabla f(a), z \rangle = 0;$$

- 4 *if f is a polynomial and X is semialgebraic, then $\Sigma_X f$ is a semialgebraic set and $f(\Sigma_X f)$ is a finite set.*

Let $X \subset \mathbb{R}^n$ be a **compact convex semialgebraic set**.

Using a translation and a dilatation we may assume that X is contained in a ball of radius $R = 1/2$ centered at zero.

Replacing f by $f + c$, where c is a constant large enough we may assume that $m = \inf\{f(x) : x \in X\} = D > 0$, where D is an upper bound for the absolute value of the first and the second derivatives of f . Then we have $\mathcal{N}(m, 2R, D) = 6$. So, for $N = 6$ and some $\mu > 0$ the function

$$\varphi_{N,\xi}(x) := (1 + |x - \xi|^2)^N f(x)$$

is μ -strongly convex on X for any $\xi \in X$.

Let $X \subset \mathbb{R}^n$ be a **compact convex semialgebraic set**.

Using a translation and a dilatation we may assume that X is contained in a ball of radius $R = 1/2$ centered at zero.

Replacing f by $f + c$, where c is a constant large enough we may assume that $m = \inf\{f(x) : x \in X\} = D > 0$, where D is an upper bound for the absolute value of the first and the second derivatives of f . Then we have $\mathcal{N}(m, 2R, D) = 6$. So, for $N = 6$ and some $\mu > 0$ the function

$$\varphi_{N,\xi}(x) := (1 + |x - \xi|^2)^N f(x)$$

is μ -strongly convex on X for any $\xi \in X$.

Let $X \subset \mathbb{R}^n$ be a **compact convex semialgebraic set**.

Using a translation and a dilatation we may assume that X is contained in a ball of radius $R = 1/2$ centered at zero.

Replacing f by $f + c$, where c is a constant large enough we may assume that $m = \inf\{f(x) : x \in X\} = D > 0$, where D is an upper bound for the absolute value of the first and the second derivatives of f . Then we have $\mathcal{N}(m, 2R, D) = 6$. So, for $N = 6$ and some $\mu > 0$ the function

$$\varphi_{N,\xi}(x) := (1 + |x - \xi|^2)^N f(x)$$

is μ -strongly convex on X for any $\xi \in X$.

For a strictly convex function φ on a convex closed set X there is a unique point $\operatorname{argmin}_X \varphi$ at which φ attains its minimum on X .

Choose an arbitrary point $a_0 \in X$, and by induction set

$$(1.1) \quad a_\nu := \operatorname{argmin}_X \varphi_{N, a_{\nu-1}}.$$

The main corollary of the convexification method is

Theorem (B, KS 2015)

Let $X \subset \mathbb{R}^n$ be a compact convex semialgebraic set and $f : \mathbb{R}^n \rightarrow \mathbb{R}$ a polynomial positive on X . Let a_ν be the sequence defined by (1.1) with $a_0 \in X$. Then the limit

$$a^* = \lim_{\nu \rightarrow \infty} a_\nu$$

exists, and $a^ \in \Sigma_X f$.*

For a strictly convex function φ on a convex closed set X there is a unique point $\operatorname{argmin}_X \varphi$ at which φ attains its minimum on X .

Choose an arbitrary point $a_0 \in X$, and by induction set

$$(1.1) \quad a_\nu := \operatorname{argmin}_X \varphi_{N, a_{\nu-1}}.$$

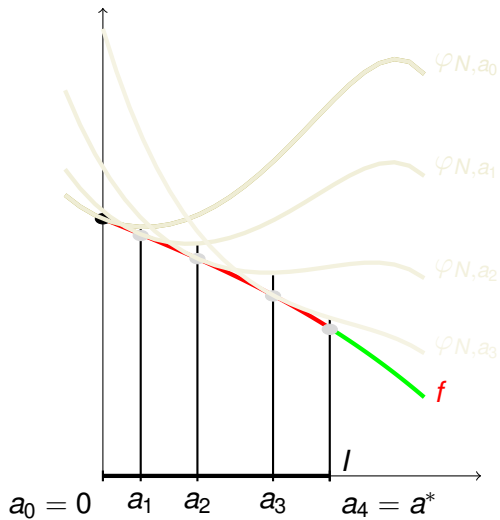
The main corollary of the convexification method is

Theorem (B, KS 2015)

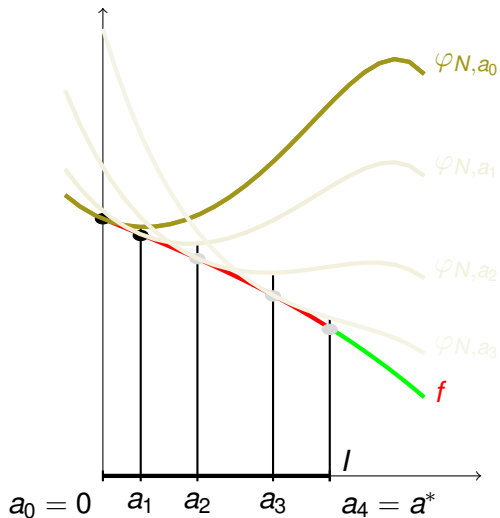
Let $X \subset \mathbb{R}^n$ be a compact convex semialgebraic set and $f : \mathbb{R}^n \rightarrow \mathbb{R}$ a polynomial positive on X . Let a_ν be the sequence defined by (1.1) with $a_0 \in X$. Then the limit

$$a^* = \lim_{\nu \rightarrow \infty} a_\nu$$

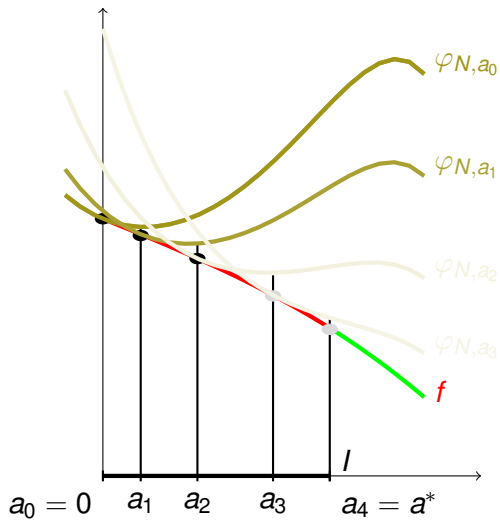
exists, and $a^ \in \Sigma_X f$.*



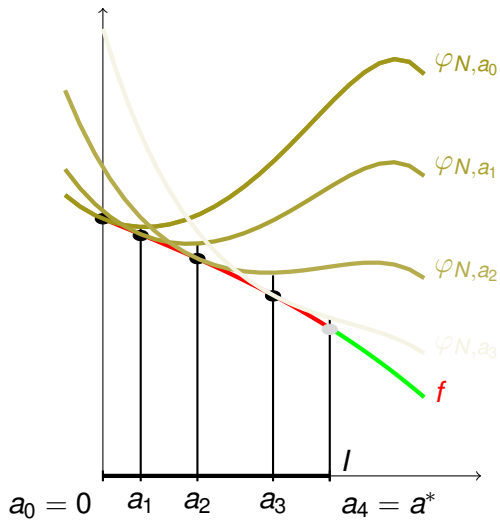
$$\varphi_{N,\xi}(x) = (1 + |x - \xi|^2)^N f(x).$$



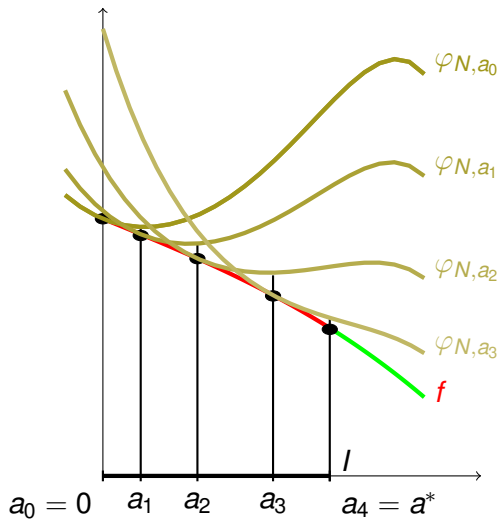
$$\varphi_{N,\xi}(x) = (1 + |x - \xi|^2)^N f(x).$$



$$\varphi_{N,\xi}(x) = (1 + |x - \xi|^2)^N f(x).$$



$$\varphi_{N,\xi}(x) = (1 + |x - \xi|^2)^N f(x).$$



$$\varphi_{N, \xi}(x) = (1 + |x - \xi|^2)^N f(x).$$

Key points in the proof of Theorem A.

Step 1. Assume that $a^* = \lim_{\nu \rightarrow \infty} a_\nu$ exists, we prove that $a^* \in \Sigma_X f$.

The main difficulty is to prove that $\lim_{\nu \rightarrow \infty} a_\nu$ exists.

Step 2. From the definition of $\varphi_{N,\xi}$ we obtain: for any $\nu \in \mathbb{N}$ we have

$$|a_{\nu+1} - a_\nu| = \text{dist}(a_\nu, f^{-1}(f(a_{\nu+1})) \cap X).$$

Step 3. From Theorem 3 we obtain: for any $\nu \in \mathbb{N}$ we have

$$f(a_{\nu+1}) \leq \frac{f(a_\nu) - \frac{\mu}{2}|a_{\nu+1} - a_\nu|^2}{(1 + |a_{\nu+1} - a_\nu|^2)^N}.$$

In particular the sequence $f(a_\nu)$ is decreasing.

Key points in the proof of Theorem A.

Step 1. Assume that $a^* = \lim_{\nu \rightarrow \infty} a_\nu$ exists, we prove that $a^* \in \Sigma_X f$.

The **main difficulty** is to prove that $\lim_{\nu \rightarrow \infty} a_\nu$ exists.

Step 2. From the definition of $\varphi_{N,\xi}$ we obtain: for any $\nu \in \mathbb{N}$ we have

$$|a_{\nu+1} - a_\nu| = \text{dist}(a_\nu, f^{-1}(f(a_{\nu+1})) \cap X).$$

Step 3. From Theorem 3 we obtain: for any $\nu \in \mathbb{N}$ we have

$$f(a_{\nu+1}) \leq \frac{f(a_\nu) - \frac{\mu}{2}|a_{\nu+1} - a_\nu|^2}{(1 + |a_{\nu+1} - a_\nu|^2)^N}.$$

In particular the sequence $f(a_\nu)$ is decreasing.

Key points in the proof of Theorem A.

Step 1. Assume that $a^* = \lim_{\nu \rightarrow \infty} a_\nu$ exists, we prove that $a^* \in \Sigma_X f$.

The **main difficulty** is to prove that $\lim_{\nu \rightarrow \infty} a_\nu$ exists.

Step 2. From the definition of $\varphi_{N,\xi}$ we obtain: for any $\nu \in \mathbb{N}$ we have

$$|a_{\nu+1} - a_\nu| = \text{dist}(a_\nu, f^{-1}(f(a_{\nu+1})) \cap X).$$

Step 3. From Theorem 3 we obtain: for any $\nu \in \mathbb{N}$ we have

$$f(a_{\nu+1}) \leq \frac{f(a_\nu) - \frac{\mu}{2}|a_{\nu+1} - a_\nu|^2}{(1 + |a_{\nu+1} - a_\nu|^2)^N}.$$

In particular the sequence $f(a_\nu)$ is decreasing.

Step 4. A key point in the proof is the use of the **Comparison Principle** due to **D. D'Acunto** and **K. K** (2006).

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be a polynomial and let $M \subset \mathbb{R}^n$ be a smooth bounded semialgebraic set. Let $\nabla f(x)$ denote the gradient of f with respect to the standard Euclidean scalar product, and

$\nabla_M f(x)$ - the projection of $\nabla f(x)$ on $T_x M$, the tangent space to M at x .

Let $\Gamma_M \subset \overline{M}$ be a semialgebraic curve meeting each level set of f and such that for every point $y \in \Gamma$ we have

$$|\nabla_M f(y)| \leq |\nabla_M f(x)| \quad \text{for all } x \in f^{-1}(f(y)).$$

By standard arguments (semialgebraic choice) such a curve always exists; it is called a *talweg* or *a ridge-valley line of f in X* .

Lemma (Comparison Principle)

For every pair of values $a < b$ taken by f , the length of any trajectory of ∇f lying in $f^{-1}((a, b)) \cap M$ is bounded by the length of $\Gamma_M \cap f^{-1}((a, b))$.

To prove that $\lim_{\nu \rightarrow \infty} a_\nu$ exists recall first that by Step 3. we have

$$f(a_\nu) \geq f(a_{\nu+1}) \geq \dots \geq f_* := \lim_{\nu \rightarrow \infty} f(a_\nu).$$

By Proposition 6 the set $f(\Sigma_X f)$ is finite, so we may assume that either the sequence $f(a_\nu)$ is eventually constant, or

$$(f(a_\nu), f_*) \cap f(\Sigma_X f) = \emptyset \quad \text{for } \nu \text{ large enough.}$$

Clearly in the first case, by Step 3., also the sequence a_ν is eventually constant. So we assume from now on that the sequence $f(a_\nu)$ is strictly decreasing and

$$(f(a_0), f_*) \cap f(\Sigma_X f) = \emptyset.$$

The set X is semialgebraic, so **there exists a stratification**

$$X = \bigcup_{i \in I} M_i,$$

i.e., a finite disjoint union of connected smooth semialgebraic sets, called **strata**.

Moreover $\overline{M}_i \setminus M_i$ is a union of some of the M_j 's of dimension smaller than $\dim M_i$.

We can refine this stratification in such a way that **f is of constant rank on each M_i , $i \in I$** ; then

our polynomial f restricted to M_i is either a constant or a submersion.

Let $I^* = \{i \in I : \text{rank } f|_{M_i} = 1\}$.

Note that $C_X f = \bigcup_{i \in I \setminus I^*} f(M_i)$ is a finite set. Since the sequence $f(a_\nu)$ is strictly decreasing we may assume that

$$(f(a_0), f_*) \cap C_X f = \emptyset.$$

To each M_i , $i \in I^*$, we can associate a semialgebraic curve $\Gamma_i := \Gamma_{M_i}$ which is a talweg of f in M_i . Set

$$\Gamma := \bigcup_{i \in I^*} \Gamma_i.$$

Recall that, by Step 2.,

$a_{\nu+1}$ is the point closest to a_ν on the fiber $f^{-1}(f(a_{\nu+1})) \cap X$.

To estimate $|a_{\nu+1} - a_\nu|$ we will construct a continuous curve

$\gamma_\nu : [t_\nu, t_{\nu+1}] \rightarrow X$ such that $\gamma_\nu(t_\nu) = a_\nu$ and $f(\gamma_\nu(t_{\nu+1})) = f(a_{\nu+1})$.

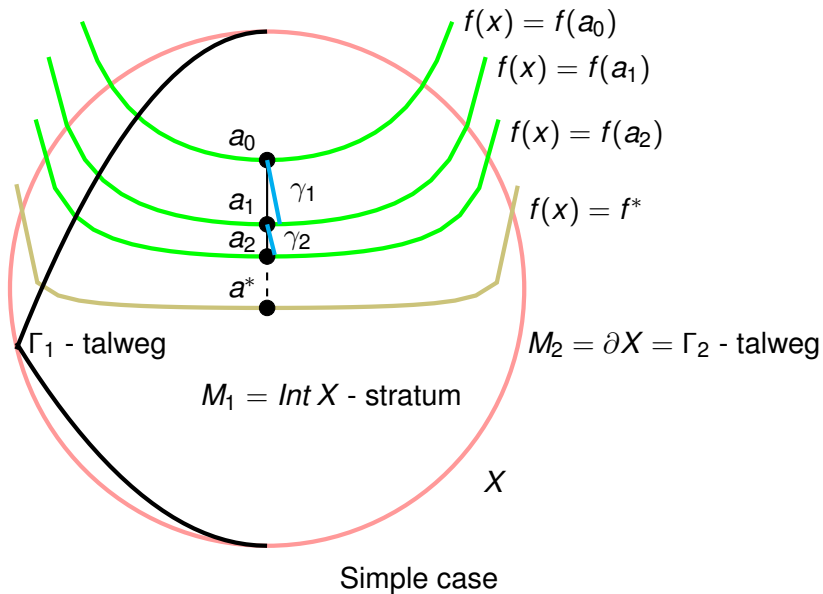
By Step 2., we will then have

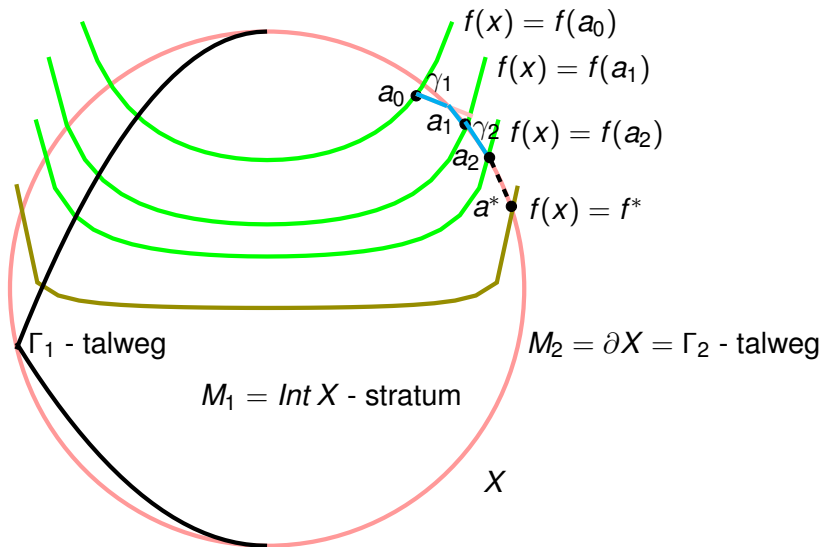
$$|a_{\nu+1} - a_\nu| \leq \text{length}(\gamma_\nu).$$

The curve γ_ν will be a piecewise trajectory of $-\nabla_{M_i} f$ (more precisely, of $-\nabla_{M_i} f / |\nabla_{M_i} f|$).

Hence, by the **Comparison Principle**,

$$|a_{\nu+1} - a_\nu| \leq \text{length}(\gamma_\nu) \leq \text{length}\{\Gamma \cap f^{-1}(f(a_{\nu+1}), f(a_\nu))\}.$$





More complicated case

Recall that Γ , being a bounded semialgebraic curve, has finite length; therefore

$$\sum_{\nu=0}^{\infty} |a_{\nu+1} - a_{\nu}| \leq \text{length}(\Gamma \cap f^{-1}(f_*, f(a_0))) < \infty.$$

So the series $\sum_{\nu=0}^{\infty} |a_{\nu+1} - a_{\nu}|$ is convergent, which implies that $a^* = \lim_{\nu \rightarrow \infty} a_{\nu}$ exists.

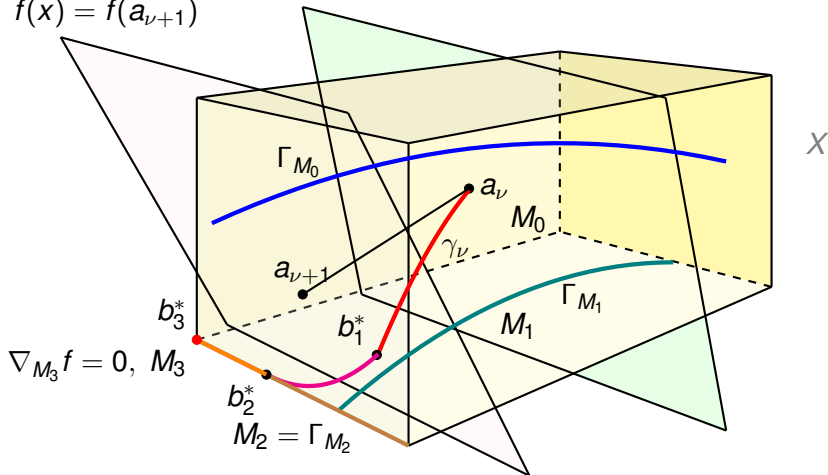
To complete the proof it is sufficient to construct the curves γ_{ν} .

We obtain this by using of Comparison Principle.

$$f(a_{\nu+1}) < f(a_{\nu})$$

$$f(x) = f(a_{\nu})$$

$$f(x) = f(a_{\nu+1})$$



3-dimensional case

I used the example by Florian Lesaint <http://creativecommons.org/licenses/by/3.0>

Let f be an analytic function in an nghb. of \overline{U} where $U \subset \mathbb{R}^n$ is open and bounded. Let $\gamma(t)$ be a trajectory of ∇f starting at some point of U . By the Łojasiewicz gradient inequality either $\gamma(t)$ leaves U or it has a limit $\gamma^* = \lim_{t \rightarrow \infty} \gamma(t) \in U$. Clearly $\nabla f(\gamma^*) = 0$.

Gradient Conjecture of R. Thom from 70's

$$\lim_{\nu \rightarrow \infty} \frac{\gamma^* - \gamma(t)}{|\gamma^* - \gamma(t)|}$$

exists.

Answered affirmatively by KK, T. Mostowski, A. Parusiński in 2000.

Discrete Thom's Gradient Conjecture

Let $X \subset \mathbb{R}^n$ be a compact convex semialgebraic set and $f : \mathbb{R}^n \rightarrow \mathbb{R}$ a polynomial positive on X . Choose an arbitrary point $a_0 \in X$, and by induction set

$$a_\nu := \operatorname{argmin}_X \varphi_{N, a_{\nu-1}}.$$

We have proved that

$$a^* = \lim_{\nu \rightarrow \infty} a_\nu$$

exists and $a^* \in \Sigma_X f$.

Conjecture

$$\lim_{\nu \rightarrow \infty} \frac{a^* - a_\nu}{|a^* - a_\nu|}$$

exists.

There is a numerical evidence supporting this conjecture.